MENG 284: Robotics & Automation Winter 2021 Course Outline

Instructor: Mr. Imtehaze Heerah, BEng. (Hons), MASc.

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Lectures (online): M (11.00 – 12.50) & Tu (9.30 – 10.20)

Labs (TEC 135/TEC 110): **X01A** – Tu (13.30 – 15.20); **X01B** – Th (15.30 – 17.20)

X01C – Th (9.30 – 11.20); **X01D** – Th (12.30 – 14.20)

Office Hours (online): M (10.00 – 10.50), Tu (10.30 – 11.20)

Course Description: Students will be introduced to the concepts of automation, as they apply to production plants and assembly processes. Sensors, controllers, actuators, materials, power-transmission systems, computer hardware and computer software will be examined. Basic principles of robotics will be considered.

Offered: Academic Term 4 (Winter)

Credit: 3

In-class workload: 3 hrs Lecture, 2 hrs Lab

Out-of-class workload: 5 hrs

Prerequisites: ECET 149, MENG 283

COURSE OBJECTIVES:

- 1. Identify robotic and automation applications
- 2. Classification of industrial robots
- 3. Identify common robotic and automated systems components such as actuators, power transmission systems, sensors and grippers
- 4. Create control programs for a 5-axis robot
- 5. Mathematically analyze planar & simple spatial robotic systems for position control
- 6. Understand and know when to use fixed, programmable and flexible automation systems including computer integrated manufacturing (CIM) and automated work cells
- 7. Identify automation support systems including: materials handling, storage & retrieval, inspection & testing, identification & tracking

COURSE OUTLINE:

- 1. Introduction to Robotics and Robotic Applications
- 2. Industrial Robots Classification Kinematic Structure, Work envelope, Control System & Actuation
- 3. Robot Kinematic Design
- 4. Electric Actuators & Control Techniques DC Motors, Stepper Motors
 - a. Speed Control (PWM, Dynamic Braking)

- b. Direction control using H-bridges
- 5. Robot Transmission Components Conventional components, Ballscrew assemblies, Harmonic Drives
- 6. Sensors
 - a. Sensor Characteristics & Construction
 - b. Position Sensors (Resistive, Capacitive, Inductive & Optical)
 - Potentiometers, LVDT, Eddy Currents sensors, Hall effect sensors, Ultrasonic sensors, Infrared sensors, Encoders (Absolute & Incremental)
 - c. Velocity & Acceleration Sensors
 - d. Force & Tactile Sensors
 - e. Vision systems
- 7. Robot controllers & programming
- 8. Kinematic analysis of Planar & SCARA Robots
 - a. Position analysis
 - b. Robot resolution
 - c. Velocity analysis
- 9. Introduction to Automation Fixed & Flexible Automation; Automated Workcells Materials Handling, Storage, Assembly, Inspection & Testing and Identification & Tracking

Техтвоокѕ:

No textbook is required for this course. All necessary material will be provided in classroom notes and handouts on the course website.

IMPORTANT NOTES:

- Refer to the course website on a regular basis for updates and deadlines
- All lab and project reports MUST be submitted prior to writing the final exam

MARKING SCHEME:

1.	Lab Work & Assignments:	20%
2.	Project I:	20%
3.	Project II:	10%
4.	Term test 1:	20%
5.	Term test 2:	15%
6.	Term test 3:	15%

GRADING SCHEME (COLLEGE POLICY):

A+	90-100%	B-	70-72%
Α	85-89%	C+	65-69%
A-	80-84%	С	60-64%
B+	77-79%	D	50-59%
В	73-76%	F	0-49%



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