

MENG 284: Robotics & Automation

Winter 2019

Course Outline

Instructor: Mr. Imtehaze Heerah, BEng. (Hons), MASc.

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Lectures: **X01A/X01B** – M (12.30 – 13.20) in CBA 212 & Th (8.30 – 10.20) in TEC 181
X02A/X02B – M (14.30 – 15.20) in CBA 271 & W (10.30 – 12.20) in CBA 210
Labs (TEC 135): **X01A** – M (15.30 – 17.20); **X01B** – Th (15.30 – 17.20)
X02A – M (9.30 – 11.20); **X02B** – Tu (9.30 – 11.20)
Office Hours: M (11.30 – 12.20), M (13.30 – 14.20), W (9.30 – 10.20), Th (14.30 – 15.20)

Course Description: Students will be introduced to the concepts of automation, as they apply to production plants and assembly processes. Sensors, controllers, actuators, materials, power-transmission systems, computer hardware and computer software will be examined. Basic principles of robotics will be considered.

Offered:	Academic Term 4 (Winter)
Credit:	3
In-class workload:	3 hrs Lecture, 2 hrs Lab
Out-of-class workload:	5 hrs
Prerequisites:	ECET 149, MENG 283

COURSE OBJECTIVES:

1. Identify robotic and automation applications
2. Classification of industrial robots
3. Identify common robotic and automated systems components such as actuators, power transmission systems, sensors and grippers
4. Create control programs for a 5-axis robot
5. Mathematically analyze planar & simple spatial robotic systems for position control
6. Understand and know when to use fixed, programmable and flexible automation systems including computer integrated manufacturing (CIM) and automated work cells
7. Identify automation support systems including: materials handling, storage & retrieval, inspection & testing, identification & tracking

COURSE OUTLINE:

1. Introduction to Robotics and Robotic Applications
2. Industrial Robots Classification – Kinematic Structure, Work envelope, Control System & Actuation
3. Robot Kinematic Design
4. Electric Actuators & Control Techniques - DC Motors, Stepper Motors

- a. Speed Control (PWM, Dynamic Braking & Plugging)
 - b. Direction control using H-bridges
5. Robot Transmission Components - Conventional components, Ballscrew assemblies, Harmonic Drives
6. Sensors
 - a. Sensor Characteristics & Construction
 - b. Position Sensors (Resistive, Capacitive, Inductive & Optical)
 - Potentiometers, LVDT, Eddy Currents sensors, Hall effect sensors, Ultrasonic sensors, Infrared sensors, Encoders (Absolute & Incremental)
 - c. Velocity & Acceleration Sensors
 - d. Force & Tactile Sensors
 - e. Vision systems
7. Robot controllers & programming
8. Kinematic analysis of Planar & SCARA Robots
 - a. Position analysis
 - b. Robot resolution
 - c. Velocity analysis
9. Introduction to Automation – Fixed & Flexible Automation; Automated Workcells - Materials Handling, Storage, Assembly, Inspection & Testing and Identification & Tracking
10. Overview of Automation Systems – Flexible Manufacturing Systems & Computer Integrated Manufacturing Systems

TEXTBOOKS:

No textbook is required for this course. All necessary material will be provided in classroom notes and handouts on the course website.

IMPORTANT NOTES:

- Refer to the course website on a regular basis for updates and deadlines
- All lab and project reports MUST be submitted prior to writing the final exam

MARKING SCHEME:

1. Lab Work & Assignments:	20%
2. Project I:	20%
3. Project II:	10%
4. Midterm:	20%
5. Final Exam:	30%

GRADING SCHEME (COLLEGE POLICY):

A+	90-100%	B-	70-72%
A	85-89%	C+	65-69%
A-	80-84%	C	60-64%
B+	77-79%	D	50-59%
B	73-76%	F	0-49%



Immediate, Urgent, or Emergency Support

If you or someone you know requires immediate, urgent, or emergency support (e.g. illness, injury, thoughts of suicide, sexual assault, etc.), **SEEK HELP**. Resource contacts @ <http://camosun.ca/about/mental-health/emergency.html> or <http://camosun.ca/services/sexual-violence/get-support.html#urgent>

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