

Math 252

Introduction to Differential Equations

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Textbook

Dennis G. Zill, A First Course in Differential Equations with Modeling Applications, 7th

Edition, Brooks/Cole, 2001.

Evaluation

- Four tests: 50%
- Comprehensive final exam: 50%

Tentative Schedule

Test 1 October 20th Test 2 November 3rd

Test 3 November 17th Test 4 December 1st

Final exams are held from December 13 - 17. You must be available at the scheduled time.

The following percentage conversion to letter grade will be used:

Percentage: 0–49 50–59 60–64 65–69 70–74 75–79 80–84 85–89 90–94 95–100

Letter grade: F D C C+ B- B B+ A- A A+

Course Outline

1. Introduction to Differential Equations

- Definitions and Terminology (section 1.1)
- Initial-Value Problems (section 1.2)

2. First-Order Differential Equations

- Separable Variables (section 2.2)
- Linear Equations (section 2.3)
- Exact Equations (section 2.4)
- Solutions by Substitutions (section 2.5)

3. Differential Equations of Higher-Order

- Preliminary Theory: Linear Equations (section 4.1)
- Reduction of Order (section 4.2)
- Homogeneous Linear Equations with Constant Coefficients (section 4.3)
- Undetermined Coefficients — Superposition Approach (section 4.4)
- Variation of Parameters (section 4.6)
- Cauchy-Euler Equations (section 4.7)

4. Modeling with Higher-Order Differential Equations

- Linear Equations: Initial-Value Problems (section 5.1)
- Spring/Mass Systems: Free Undamped Motion (5.1.1)
- Spring/Mass Systems: Damped Motion (5.1.2)
- Spring/Mass Systems: Driven Motion (5.1.3)
- Series Circuit Analogue (5.1.4)

5. Series Solutions of Linear Equations

- Solutions About Ordinary Points (section 6.1)
- Solutions about Singular Points (section 6.2)
- 6. Laplace Transforms
 - Definition of the Laplace Transform (section 7.1)
 - Inverse Transform and Transform of Derivatives (section 7.2)
 - Translation Theorems (section 7.3)
 - Additional Operational Properties (section 7.4)
 - Dirac Delta (section 7.5)
- 7. Systems of Linear First-Order Differential Equations
 - Preliminary Theory (section 8.1)
 - Homogeneous Linear Systems with Constant Coefficients (section 8.2)
 - Variation of Parameters (section 8.3)
 - Matrix Exponential (section 8.4)
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